Author Index to Volume 1

Abdel-Rahman, Z. Z.: See Shahinpoor, M.
Ahluwalia, R. S., and Hsu, E. Y.: Sensor-Based Obstruction Avoidance Technique for a Mobile Robot, 331
Akkermans, M.: See Van Gool, L.
Arimoto, S., Kawamura, S., and Miyazaki, F.: Bettering Operation of Robots by Learning, 123

Beni, G., and Hackwood, S.: Editorial, 1, 119

Chung, M. J.: See Lee, C. S. G.

Donne, J. D.: See Wongchaisuwat, C.
Driels, M.: See Huang, M.
—, and Yang, Z. H.: Alternative Methods for the Analysis of Robot Arm Dynamics, 351
—, Huang, M., Liscano, R., and Michael, K.: Brief Report: The Use of Visual Feedback for the Acquisition of Pseudorandomly Oriented Parts, 193

Freund, E., and Hoyer, H.: Collision Avoidance for Industrial Robots with Arbitrary Motion, 317
Fu, K. S.: See Lin, W. C.

Guo, T. H., and Koivo, A. J.: On a Linearized Model and Adaptive Controller Implementation for Manipulator Motion, 141

Hackwood, S.: See Beni, G.
Hemami, H.: See Wongchaisuwat, C.
—, and Zheng, Y.-F.: Dynamics and Control of Motion of the Ground and in the Air with Application to Biped Robots, 101
Henderson, T., and Shilcrat, E.: Logical Sensor Systems, 169
Hoyer, H.: See Freund, E.
Hsu, E. Y.: See Ahluwalia, R. S.
Huang, M., and Driels, M.: Brief Report: High-Performance, Low-Cost Analog Data Processing and Control Using a 16-Bit Single-Board Microcomputer, 205
—: See Driels, M.

Kanada, T.: See Okada, T.
Kawamura, S.: See Arimoto, S.
Koivo, A. J.: See Guo, T. H.

Lee, B. H.: See Lee, C. S. G.
Lee, C. S. G., Chung, M. J., and Lee, B. H.: An Approach of Adaptive Control for Robot Manipulators, 27
Lin, W. C., Fu, K. S., and Sederberg, T.: Estimation of Three-Dimensional Object Orientation for Computer Vision Systems with Feedback, 59
Liscano, R.: See Driels, M.
Luh, J. Y. S.: A Scheme for Collision Avoidance with Minimum Distance Traveling for Industrial Robots, 5

Michael, K.: See Driels, M.
Miyazaki, F.: See Arimoto, S.

Oh, S.-Y., and Orin, D.: An Inverse Kinematic Solution for Kinematically Redundant Robot Manipulators, 235
Okada, T., and Kanade, T.: Appropriate Lengths Between Phalanges of Multijointed Fingers for Stable Grasping, 223
Oosterlinck, A.: See Van Gool, L.
Orin, D.: See Oh, S.-Y.
Ozguner, U.: See Wongchaisuwat, C.

Pinson, L. J.: Robot Vision: An Evaluation of Imaging Sensors, 263

Sederberg, T.: See Lin, W. C.
Shahinpoor, M., and Abdel-Rahman, S. Z.: Generalized Algorithm for Computing the 4-3-4 *N*-Axis Robotic Trajectory, 395
Shilcrat, E.: See Henderson, T.
Stokić, D.: See Vukobratović, M.
Swartz, N. M: Arm Dynamics Simulation, 83

Van Gool, L., Van Thillo, M., Akkermans, M., and Oosterlinck, A.: The Creation of Line Drawings as a Basis for Feature-Based Stereo Vision, 251
Van Thillo, M.: See Van Gool, L.
Vukobratović, M., and Stokić D.: Nonadaptive Dynamic Control for Manipulation Robots: Centralized or Decentralized Control, 379

Wongchaisuwat, C., Donne, J. D., Ozguner, U., and Hemami, H.: Control of a Planar Arm by Nonlinear Feedback Gains, 157

Yang, Z. H.: See Driels, M. R.

Zheng, Y.-F.: See Hemami, H.

Journal of Robotic Systems

Contents
Volume 1, 1984

Number 1, Spring 1984

1 Editorial
Gerardo Beni and Susan Hackwood

5 A Scheme for Collision Avoidance with Minimum Distance Traveling for Industrial Robots
J. Y. S. Luh

27 An Approach of Adaptive Control for Robot Manipulators
C. S. G. Lee, M. J. Chung, and B. H. Lee

59 Estimation of Three-Dimensional Object Orientation for Computer Vision Systems with Feedback
W. C. Lin, K. S. Fu, and T. Sederberg

83 Arm Dynamics Simulation
Neil M. Swartz

101 Dynamics and Control of Motion on the Ground and in the Air with Application to Biped Robots
Hooshang Hemami and Yuan-Fang Zheng

117 Information for Contributors

Number 2, Summer 1984

119 Editorial
Gerardo Beni and Susan Hackwood

123 Bettering Operation of Robots by Learning
Suguru Arimoto, Sadao Kawamura, and Fumio Miyazaki

141 On a Linearized Model and Adaptive Controller Implementation for Manipulator Motion
T. H. Guo and A. J. Koivo

157 Control of a Planar Arm by Nonlinear Feedback Gains
C. Wongchaisuwat, J. D. Donne, U. Ozguner, and H. Hemami

169 Logical Sensor Systems
Tom Henderson and Esther Shilcrat

Brief Reports

195 The Use of Visual Feedback for the Acquisition of Pseudorandomly Oriented Parts
Morris Driels, Mingzen Huang, Ramiro Liscano, and Kim Michael

205 High-Performance, Low-Cost Analog Data Processing and Control Using a 16-Bit Single-Board Microcomputer
M. Huang and M. Driels

221 Information for Contributors

Number 3, Fall 1984

223 Appropriate Lengths Between Phalanges of Multijointed Fingers for Stable Grasping
Tokuji Okada and Takeo Kanade

235 An Inverse Kinematic Solution for Kinematically Redundant Robot Manipulators
Se-Young Oh and David Orin

251 The Creation of Line Drawings as a Basis for Feature-Based Stereo Vision
L. Van Gool, M. Van Thillo, M. Akkermans, and A. Oosterlinck

263 Robot Vision: An Evaluation of Imaging Sensors
Lewis J. Pinson

315 Information for Contributors

Number 4, Winter 1984

317 Collision Avoidance for Industrial Robots with Arbitrary Motion
E. Freund and H. Hoyer

331 Sensor-Based Obstruction Avoidance Technique for a Mobile Robot
R. S. Ahluwalia and E. Y. Hsu

351 Alternative Methods for the Analysis of Robot Arm Dynamics
M. R. Driels and Z. H. Yang

379 Nonadaptive Dynamic Control for Manipulation Robots: Centralized or Decentralized Control
Miomir Vukobratović and Dragan Stokić

395 Generalized Algorithm for Computing the 4-3-4 *N*-Axis Robotic Trajectory
M. Shahinpoor and S. Z. Abdel-Rahman

421 Author Index to Volume 1

423 Information for Contributors

i Volume Contents